**Basic Scribbler Bot Commands**

**getName()**

Returns the name of the robot to the screen

**backward(SPEED)**

Move backwards at SPEED (value in the range -1.0...1.0).

**backward(SPEED,SECONDS)**

Move backwards at SPEED (value in the range -1.0...1.0) for a time given in

SECONDS, then stop.

**forward(SPEED)**

Move forward at SPEED (value in the range -1.0..1.0).

**forward(SPEED,TIME)**

Move forward at SPEED (value in the range -1.0...1.0) for a time given in

seconds, then stop.

**move(TRANSLATE, ROTATE)**

Move at the TRANSLATE and ROTATE speeds (value in the range -1.0...1.0).

**translate(SPEED)**

Move in a straight line at SPEED (value in the range -1.0...1.0). Negative

values specify backward movement and positive values specify forward

movement.

**rotate(SPEED)**

Rotates at SPEED (value in the range -1.0...1.0). Negative values rotate right

(clockwise) and positive values rotate left (counter-clockwise).

**stop()**

Stops the robot.

**turnLeft(SPEED)**

Turn left at SPEED (value in the range -1.0...1.0)

**turnLeft(SPEED,SECONDS)**

Turn left at SPEED (value in the range -1.0..1.0) for a time given in seconds,

then stops.

**turnRight(SPEED)**

Turn right at SPEED (value in the range -1.0..1.0)

**turnRight(SPEED,SECONDS)**

Turn right at SPEED (value in the range -1.0..1.0) for a time given in seconds,

then stops.

**wait(TIME)**

Pause for the given amount of TIME seconds. TIME can be a decimal number.